

Recall:

We have

$$\left(\frac{d}{dt}\right)^k (e^{\lambda t} y) = e^{\lambda t} \left[\left(\frac{d}{dt} + \lambda\right)^k y\right]$$

using the computation:

$$\frac{d}{dt} (e^f y) = e^f \left(\frac{df}{dt} + \frac{dy}{dt}\right)$$

for general function f .

- Let $a_n y^{(n)} + \dots + a_0 y = 0$ with
Let $f(r) = a_n (r-r_1) \dots (r-r_s) (r-r_0)^{n-s}$

Last time: We show $f\left(\frac{d}{dt}\right) (t^k e^{r_0 t}) = 0$

for $k < n-s$.

$\Rightarrow e^{r_0 t}, t e^{r_0 t}, \dots, t^{n-s-1} e^{r_0 t}$ are solutions
to the ODE.

Fundamental set:

$$e^{r_1 t}, e^{r_2 t}, \dots, e^{r_s t}, e^{r_0 t}, t e^{r_0 t}, \dots, t^{n-s-1} e^{r_0 t}$$

Next: we consider

$$f(r) = a_n(r-r_1) \dots (r-r_s) (r-\lambda)^k (r-\bar{\lambda})^k$$

with $2k+s=n$.

Claim: $e^{\lambda t}, \dots, t^{k-1} e^{\lambda t}$
 $e^{\bar{\lambda} t}, \dots, t^{k-1} e^{\bar{\lambda} t}$ are solutions

Reason: if we write

$$f\left(\frac{d}{dt}\right) = a_n\left(\frac{d}{dt} - r_1\right) \dots \left(\frac{d}{dt} - r_s\right) \left(\frac{d}{dt} - \lambda\right)^k \left(\frac{d}{dt} - \bar{\lambda}\right)^k$$

then $a_n y^{(n)} + \dots + a_1 y' + a_0 y = f\left(\frac{d}{dt}\right)(y)$

operator

Observe: $\left(e^{\lambda t} \frac{d}{dt} e^{-\lambda t}\right)(y) = \left(\frac{d}{dt} - \lambda\right)(y)$

operator!

\therefore we can rewrite

$$\begin{aligned} \left(\frac{d}{dt} - \lambda\right)^k &= \left(e^{\lambda t} \frac{d}{dt} e^{-\lambda t}\right)^k \\ &= \left(e^{\lambda t} \frac{d}{dt} e^{-\lambda t}\right) \left(e^{\lambda t} \frac{d}{dt} e^{-\lambda t}\right) \dots \left(e^{\lambda t} \frac{d}{dt} e^{-\lambda t}\right) \end{aligned}$$

$$= e^{\lambda t} \left(\frac{d}{dt}\right)^k e^{-\lambda t}$$

$$\begin{aligned} \therefore \left(\frac{d}{dt} - \lambda\right)^k (t^m e^{\lambda t}) &= e^{\lambda t} \left(\frac{d}{dt}\right)^k (t^m) \\ &= 0 \quad \text{if } m < k \end{aligned}$$

Similarly: $(\frac{d}{dt} - \bar{\lambda})^k = e^{\bar{\lambda}t} (\frac{d}{dt})^k e^{-\bar{\lambda}t}$

$$(\frac{d}{dt} - \bar{\lambda})^k (e^{\bar{\lambda}t} t^m) = e^{\bar{\lambda}t} (\frac{d}{dt})^k (t^m) = 0$$

if $m < k$.

To obtain \mathbb{R} -valued solution: write $\lambda = \alpha + i\mu$

$$e^{\alpha t} \cos \mu t = \left(\frac{e^{\lambda t} + e^{\bar{\lambda}t}}{2} \right) \dots t^{k-1} e^{\alpha t} \cos \mu t$$

$$e^{\alpha t} \sin \mu t = \left(\frac{e^{\lambda t} - e^{\bar{\lambda}t}}{2i} \right) \dots t^{k-1} e^{\alpha t} \sin \mu t.$$

Example: Let $f(r) = (r^2 + 1)(r - 1)^2(r + 2)$

then we consider solution for $f(\frac{d}{dt})(y) = 0$

We have: $r_1 = 1$ with multiplicity 2

$r_2 = -2$ " " 1.

$\lambda = i, \bar{\lambda} = -i$ " " 1.

$\therefore y_1 = e^t, y_2 = e^{-2t}, y_3 = \cos t, y_4 = \sin t.$

Ex: compute the Wronskian and show that they are fundamental set of sol.

Example 2: $f(r) = (r^2 + 2r + 2)^2 (r - 1)^3$

Consider the equation: $f\left(\frac{d}{dt}\right)(y) = 0$.

We first solve $f(r) = 0$, which gives us

$$r_1 = 1 \quad \text{with multiplicity} = 3$$

$$\lambda = -1 + i, \bar{\lambda} = -1 - i \quad \text{mult:} = 1$$

Hence we have

$$y_1(t) = e^t, \quad y_2 = te^t, \quad y_3 = t^2 e^t$$

$$y_4(t) = e^{-t} \cos t, \quad y_5 = e^{-t} \sin t$$

Recall: Among all these examples, we have to prove that y_1, \dots, y_n is a fundamental set.

Thm: y_1, \dots, y_n solution to $y^{(n)} + p_{n-1}(t)y^{(n-1)} + \dots + p_0(t)y = 0$

IFAE: 1) y_1, \dots, y_n linearly independent.

2) $\text{Span}(y_1, \dots, y_n) = \mathcal{S}$

3) $W(y_1, \dots, y_n)(t_0) \neq 0$ for some $t_0 \in I$.

Eg. $f(r) = a_n (r-r_1)^2 (r-r_2)^3$ s.t. $2+3=n$

$\leadsto e^{r_1 t}, te^{r_1 t}, e^{r_2 t}, te^{r_2 t}, t^2 e^{r_2 t}$

Want: they are linearly independent.

Assume:

$$0 = C_1 e^{r_1 t} + C_2 t e^{r_1 t} + C_3 e^{r_2 t} + C_4 t e^{r_2 t} + C_5 t^2 e^{r_2 t}$$

Want: $C_i = 0$ for $i = 1, \dots, 5$.

Try: $0 = C_1 + C_2 t + C_3 e^{\hat{r}t} + C_4 t e^{\hat{r}t} + C_5 t^2 e^{\hat{r}t}$.
with $\hat{r} = r_2 - r_1$

differentiate:

$$C_2 + (\hat{r} C_3 + C_4) e^{\hat{r}t} + (\hat{r} C_4 + 2C_5) t e^{\hat{r}t} + \hat{r} C_5 t^2 e^{\hat{r}t}$$

Need: $1, e^{\hat{r}t}, t e^{\hat{r}t}, t^2 e^{\hat{r}t}$ linearly indep.

True: by induction

$$\Rightarrow C_2 = 0, \hat{r} C_3 + C_4 = 0, \hat{r} C_4 + 2C_5 = 0, \hat{r} C_5 = 0$$

$$\Rightarrow C_2 = C_3 = C_4 = C_5 = 0$$

Back to original eqt: $\Rightarrow C_1 = 0$

E.g. More generally:

$$f(r) = a_n (r - r_1)^2 (r - \lambda)^2 (r - \bar{\lambda})^2.$$

$\alpha + i\mu$

We have

$$e^{r_1 t}, t e^{r_1 t}, e^{\alpha t} \cos \mu t, e^{\alpha t} \sin \mu t, t e^{\alpha t} \cos \mu t, t e^{\alpha t} \sin \mu t.$$

Want: They are linearly independent!

First: we show

$$e^{r_1 t}, t e^{r_1 t}, e^{\lambda t}, t e^{\lambda t}, e^{\bar{\lambda} t}, t e^{\bar{\lambda} t}$$

linearly independent over \mathbb{C}

- same induction proof as previous example.

Then: writing $e^{\alpha t} \cos \mu t = \frac{e^{\lambda t} + e^{\bar{\lambda} t}}{2}$

$$e^{\alpha t} \sin \mu t = \frac{e^{\lambda t} - e^{\bar{\lambda} t}}{2i}$$

$$\Rightarrow e^{r_1 t}, t e^{r_1 t}, e^{\alpha t} \cos \mu t, e^{\alpha t} \sin \mu t, t e^{\alpha t} \cos \mu t, t e^{\alpha t} \sin \mu t$$

linearly independent over $\mathbb{C} \Rightarrow$ l.i. over \mathbb{R}

§ Inhomogeneous equation with constant coefficient

$$(*) \quad a_n y^{(n)} + \dots + a_1 y' + a_0 y = r(t).$$

Prop:

General solution:

$$C_1 y_1 + \dots + C_n y_n + Y(t)$$

↑ particular solution

↓ solutions to the homogeneous equation!

Goals to find $Y(t)$

Three cases:

Case i) $r(t) = P_k(t)$

Case ii) $r(t) = e^{\alpha t} P_k(t)$

Case iii) $r(t) = e^{\alpha t} P_k(t) \cos \omega t$ or $e^{\alpha t} P_k(t) \sin \omega t$.

Case i) Write $P_k(t) = A_0 t + \dots + A_k t^k$.

And let $Y(t) = Q_k(t) = B_0 t + \dots + B_k t^k$

Want: Solve for B_i 's.

Ex:

$$a_3 y^{(3)} + a_2 y^{(2)} + a_1 y' + a_0 y = P_k(t).$$

$$\begin{aligned} \rightarrow Y' &= B_1 + 2B_2t + 3B_3t^2 + \dots + (j+1)B_jt^j + \dots + lB_lt^{l-1} \\ Y'' &= 2B_2 + 3 \cdot 2 B_3t + \dots + (j+2)(j+1)B_{j+2}t^j \\ &\quad + \dots + l(l-1)B_lt^{l-2} \end{aligned}$$

$$Y^{(3)} = 3 \cdot 2 B_3 + \dots + (j+3)(j+2)(j+1)B_{j+3}t^j + \dots + l(l-1)(l-2)B_lt^{l-3}$$

\therefore coefficient of t^j in $f\left(\frac{d}{dt}\right)(Y)$:

$$a_3 \frac{(j+3)!}{j!} B_{j+3} + a_2 \frac{(j+2)!}{j!} B_{j+2} + a_1 \frac{(j+1)!}{j!} B_{j+1} + a_0 \frac{j!}{j!} B_j$$

Equation to solve:

$$a_3 \frac{(j+3)!}{j!} B_{j+3} + a_2 \frac{(j+2)!}{j!} B_{j+2} + a_1 \frac{(j+1)!}{j!} B_{j+1} + a_0 \frac{j!}{j!} B_j = A_j.$$

4 cases:

1) $a_0 \neq 0$, then we can solve it with $l=k$:

invertible \rightarrow

$$\begin{pmatrix} a_0 & a_1 & 2a_2 & \dots & \dots \\ & & & & \vdots \\ & & & & a_2 \frac{k!}{(k-2)!} \\ & & & & a_1 k \\ & & & & a_0 \end{pmatrix} \begin{pmatrix} B_0 \\ \vdots \\ \vdots \\ B_k \end{pmatrix} = \begin{pmatrix} A_0 \\ \vdots \\ \vdots \\ A_k \end{pmatrix}$$

2) $a_0 = 0, a_1 \neq 0$, we can solve it with $l = k+1$.

$$\begin{pmatrix} a_1 & & & \\ & \circ & & \\ & & \ddots & \\ & & & a_1 (k+1) \end{pmatrix} * \begin{pmatrix} B_1 \\ \vdots \\ B_{k+1} \end{pmatrix} = \begin{pmatrix} A_0 \\ \vdots \\ A_k \end{pmatrix}$$

3) $a_0 = a_1 = 0, a_2 \neq 0$, take $l = k+2$

$$\begin{pmatrix} 2a_2 & & & \\ & \circ & & \\ & & \ddots & \\ & & & a_2 \frac{(k+2)!}{k!} \end{pmatrix} * \begin{pmatrix} B_2 \\ \vdots \\ B_{k+2} \end{pmatrix} = \begin{pmatrix} A_0 \\ \vdots \\ A_k \end{pmatrix}$$

4) $a_0 = a_1 = a_2 = 0$, we take $l = k+3$,

$$\begin{pmatrix} 6a_3 & & & \\ & \circ & & \\ & & \ddots & \\ & & & a_3 \frac{(k+3)!}{k!} \end{pmatrix} * \begin{pmatrix} B_3 \\ \vdots \\ B_{k+3} \end{pmatrix} = \begin{pmatrix} A_0 \\ \vdots \\ A_k \end{pmatrix}$$

In general:

For $f(r) = a_n r^n + \dots + a_0$

and consider $f\left(\frac{d}{dt}\right)(Y) = P_k(t)$.

General equation:

$$a_n \frac{(j+n)!}{j!} B_{j+n} + a_{n-1} \frac{(j+n-1)!}{j!} B_{j+n-1} + \dots + a_0 \frac{j!}{j!} B_j = A_j$$

n Cases: $a_0 = \dots = a_m = 0, a_{m+1} \neq 0$

We can solve it will $l = k+m+1$

• Next we consider $r(t) = e^{\alpha t} P_k(t) = A_0 + \dots + A_k t^k$

Try: $Y(t) = e^{\alpha t} Q_l(t) = B_0 + \dots + B_l t^l$